Supplementary Material for Dynamic Principal Component Analysis in High Dimensions"

S.1 Algorithm

Practitioners may use the retraction-based proximal gradient method (ManPG) (Chen et al., 2020) to solve our manifold optimization problem (5). Denote $M = V_{p;d}$ and F(V) =

Tr f V(t)^T (t)V(t)g + kV(t)k₁ where f(V) = Tr f V(t)^T (t)V(t)g is smooth and its gradient is Lipschitz continuous with the Lipschitz constantL and h(V) = kV(t)k₁. ManPG rst computes a descent directionD_k (k-th step) by solving the following problem:

$$\min_{D} < 5 f(V_{k}); D > + \frac{1}{2t} k D k_{F}^{2} + h(V_{k} + D)$$
s:t: $D^{T} V_{k} + V_{k}^{T} D = 0;$
(S.1)

where V_k is obtained in the k-th iteration, t > 0 is a step size and D is a descent direction of F in the tangent space $T_{V_k}M$. Based on the Lagrangian function and KKT system, we get that

$$E() = A_k(D()) = 0$$
; (S.2)

where $A_k(D) = D^T V_k + V_k^T D$, $D() = \text{prox}_{th}(B())$ V_k with $B() = V_k$ $t(5 \text{ f}(V_k) A())$, A() denotes the adjoint operator of A_k , where is a d d symmetric matrix. The semi-smooth Newton method (SSN) (Xiao et al., 2018) could be used to solve (S.2).

Retraction operation is an important concept in manifold optimization, see Absil et al. (2009) for more details. There are many common retractions for the Stiefel manifold, including exponential mapping, the polar decomposition and the Cayley transformation. For

inequality and the Cauchy-Schwarz inequality we have

Denote the event $E_n = \{E_x e^{a \sum_{l=1}^{m_i} \tilde{w}_{ll} x_{lj} | x_{lkl}} < \infty\}$, where E_x means that the expectation is taken on x conditional on t_{il} . Then, it holds for all *i* by picking some appropriate w_{il} and a such that $\max_i am_i | w_{il} |$ is su ciently small, since $x_j^2(t)$ is sub-exponential uniformly in *t* by Assumption 2.

Define
$$B := \bigcap_{i=1}^{n} b_{ijk} = O(n^3 m^3 h^3 + n^3 m^4 h^4)$$
. For sumciently large n , we have

$$P \xrightarrow{\wedge}_{i=1}^{n} W_{ijk} \ge \int_{n} E_n \le \exp\{-a_n\} E \exp\{a \sum_{i=1}^{n} W_{ijk} E_n$$

$$= \exp\{-a_n\} \xrightarrow{\wedge}_{i=1}^{n} E \exp(aW_{ijk}) E_n$$

$$\le \exp\{-a_n + Ba^2\}$$
(S.6)

Note that (S.6) is minimized when $a = {}_{n}=(2B)$ and that the minimizer is $\exp\{-{}_{n}^{2}=(4B)\}$. Thus, there exists some positive constant *C* such that

$$P \bigvee_{i=1}^{k} W_{ijk} \ge {}_{n} E_{n} \le \exp -C {}_{n}^{2} = (n^{3}m^{3}h^{3} + n^{3}m^{4}h^{4}) .$$

Similarly, we obtain

$$P \quad \bigvee_{i=1}^{n} W_{ijk} \leq -n E_n \leq \exp (-C_n^2 = (n^3 m^3 h^3 + n^3 m^4 h^4)) :$$

The following obtained by a simple union bound holds for each $t \in \mathcal{T}$,

$$P \max_{j,k} \sum_{i=1}^{n} \{ W_{il} X_{ijl} X_{ikl} - E(W_{il} X_{ijl} X_{ikl}) \} \ge n E_n$$

$$\leq 2p^2 \exp -C \sum_{n=1}^{2} (n^3 m^3 h^3 + n^3 m^4 h^4) :$$

Let $_n = O\{(\log p)^{1/2}(n^3m^3h^3 + n^3m^4h^4)^{1/2}\}$. Note that $W_{il} = O_p\{(n^2m^2h^3)^{1/2}\}$ from Lemma 4, then with probability tending to 1, the event E_n holds from Assumption 4. Consequently,

$$\max_{j,k} \sum_{i=1}^{N^{n}} \{ W_{il} X_{ijl} X_{ikl} - E(W_{il} X_{ijl} X_{ikl}) \} = O_p\{ (\log p)^{1/2} (n^3 m^3 h^3 + n^3 m^4 h^4)^{1/2} \}:$$

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