



# Asymptotic distribution of nonparametric regression estimator for longitudinal functional data

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## Abstract

The estimation of a regression function by kernel method for longitudinal functional data is considered. In the context of longitudinal data analysis, a random function typically represent a subject that is often observed at a small number of time points, while in the study of functional data the random realization is usually measured on a dense grid. However, essentially the same method can be applied to both sampling plan, a well as in a number of setting lying between them. In this paper, general results are derived for the asymptotic distribution of real-valued function with argument which are functional formed by weighted average of longitudinal functional data. Asymptotic distribution for the estimator of the mean and covariance function obtained from noisy observation with the presence of within-subject correlation are studied. The asymptotic normality results are comparable to the standard rate obtained from independent data, which is illustrated in a simulation study. Besides, this paper discuss the condition associated with sampling plan, which are required for the validity of local properties of kernel-based estimator for longitudinal functional data.

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## 1. Introduction

Modern technology and advanced computing environment have facilitated the collection and analysis of high-dimensional data, or data that are repeatedly measured for a sample of subjects. The repeated measurements are often recorded over a period of time, as on an closed and bounded interval  $\mathcal{T}$ . It also could be a spacial variable, such as in image or geoscience application.

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When the data are recorded den el o e time, often b machine, the are tipicall termed f nctional or c r e data. ith one ob e r ed c r e of f nction per . bject, hile in longit . dinal t die the epeated mea . e ment . . all take place on a fe . cattered ob e r ational time point for each . bject. A ignificant int . in ic difference bet . een t . o eeting lie in the perception that f nctional data are ob e r ed in the contin . m . itho . t noi e [2,3], here a longit . dinal data are ob e r ed at parallel di trib ted time point and are often . bject to eperimental error [4]. Ho . e e r, in practice f nctional data are anal ed after smoothing noi . ob e r ation [10], hich indicate that the difference bet . een t . o e data pe . related to the . a in . hich a problem i . percei ed are arg . abl more concept . al than act . al. Therefore in thi paper, kernel-ba ed egre . ion e timator obtained from ob e r ation at discrete time point contaminated . ith mea . e ment error, rather than ob e r ation in the contin . m, are con idered for the e reali tic ea on . In the context of kernel-ba ed nonparametric egre . ion, the effect of ampling plan on the tati tical e timator are al o in e ligated.

A a t literat . e ha been de eloped in the pa t decade on the kernel-ba ed egre . ion for independent and identicall di trib ted data, for . mmar . ee Fan and Gijbel [5]. There ha been . bstantial ecent int e r t in e tending the e i tting a mptotic e . l t to f nctional or longit . dinal data [8,11,14,13,9]. The i . e ca ed b the . ithin . bject correlation are rigoro . l add e ed in thi paper. Hax and Wehd [8] t . died the Ga e r M lle e timator of the mean f nction for epeated mea . e ment ob e r ed on a e g larg id b . a . ming tational correlation t r ct . e, and ho . ed that the infl . ence of the . ithin . bject correlation on the a mptotic ariance i . of malle . order compared to the tandard rate obtained from independent data and . ill di appear . hent the correlation f nction i . differentiable at e o. O . ra mptotic di trib tion e . l t i . in fact con i tent . ith that in Hax and Wehd [8] and applicable for general co ariance t r ct . e . itho . t tational a . mption. Thi problem . a al o di c . ed b Stani . ali and Lee [12] and Lin and Carroll [9], here the . ed the he . i tic arg . ment of the local p ope . t of local pol nomial e timation and int . iti el . ignored the . ithin . bject correlation hile dei . ing the a mptotic ariance . Thi paper dei . e appropriate condition that are e q . ied for the alidit of the local p ope . t of kernel t pe e timator obtained from longit . dinal or f nctional data. The e condition al o p oide practical g ideline for ario . ampling p oced . e .

The cont . ib tion of thi paper i . the dei . ation of general a mptotic di trib tion e . l t in both one-dimen ional and . o-dimen ional smoothing context for real- al ed f nction . ith arg . ment . hich are f nctional formed b . e ighted a eage of longit . dinal or f nctional data. The e a mptotic normalit . e . l t are comparable to tho e obtained for identicall di trib ted and independent data. The e . l t are applied to the kernel-ba ed e timator of the mean and co ariance f nction . hich ield a mptotic normal di trib tion of the e e timator. In partic . lar, to the bet of o . kn . ledge, no a mptotic di trib tion e . l t are a ailable . p to date for nonparametric e timation of co ariance f nction obtained from longit . dinal or f nctional data contaminated . ith mea . e ment error. B . comparison, Hall et al. [6,7] in e ligated a mptotic p ope . tie of nonparametric kernel e timator of a t oco ariance, here the mea . e ment . e e onl . ob e r ed from a single tational tocha tic p oced . or random field. Altho gh the a mptotic di trib tion are dei . ed for random de ign in thi paper, the arg . ment can be e tended to fixed de ign and other ampling plan . ith appropriate modification, and a mptotic bia . and ariance term can al o be obtained in imilar manne . . Thi . ill p oide theoretical ba i . and practical g idance for the nonparametric anal . i of f nctional or longit . dinal data . ith important potential application . hich are ba ed on the a mptotic di trib tion . T pical e ample incl . de the con t r ction of a mptotic confidence band for egre . ion f nction and confidence region

for covariance surface, and also a fast selection of bandwidth for covariance surface estimation based on asymptotic mean squared error. Other application in the context of smoothing independent data can be explored for the smoothing of longitudinal functional data using kernel-based estimator.

The remainder of the paper is organized as follows. In Section 2, we derive the general asymptotic distribution of one- and  $d$ -dimensional smoothers obtained from longitudinal functional data for random design. The general asymptotic results are applied to commonly used kernel-type estimator of the mean curve and covariance surface in Section 3. Extension to fixed design is discussed in Section 4. A simulation study is presented to evaluate the derived asymptotic results for correlated data in Section 5. While discussion, including potential application of the resulting asymptotic normality, are offered in Section 6.

## 2. General results of asymptotic distributions for random design

In this section, we will define general functional that are kernel-weighted average of the data for one-dimensional and  $d$ -dimensional smoothing. The introduced general functional include the most commonly used type of kernel-based estimator such as Gaussian M-estimator, Nadaraya-Watson estimator, local polynomial estimator, etc. Since Nadaraya-Watson and local polynomial estimator are mostly used in practice, their asymptotic behavior in terms of bias and variance for independent data have been thoroughly studied in existing literature. However, for longitudinal functional data, particularly in regard to covariance surface estimator, the asymptotic behavior of bias and variance of the  $d$ -dimensional commonly used estimator are still largely unknown. Therefore in Section 3, the general asymptotic results developed in this section are applied to Nadaraya-Watson and local polynomial estimator in both one-dimensional and  $d$ -dimensional smoothing setting. In particular, the lack of asymptotic results for the covariance surface estimator of longitudinal functional data is an additional motivation for the definition of the  $d$ -dimensional general functional that can be applied to develop the asymptotic distribution for the estimator.

We first consider random design while extension to other sampling plan is deferred to Section 4. In classical longitudinal study, measurement are often intended to be on a regular time grid. However, since individual may miss scheduled visit, the resulting data will become sparse, where only few observation are obtained for most subject, with unequal number of repeated measurement per subject and different measurement time  $T_{ij}$  per individual. This sampling

variance  $\sigma^2$ ,

$$Y_{ij} = X_i(T_{ij}) + \varepsilon_{ij} = \mu(T_{ij}) + \sum_{k=1}^{\infty} \xi_{ik} \phi_k(T_{ij}) + \varepsilon_{ij}, \quad T_{ij} \in \mathcal{T}, \tag{1}$$

where  $E\varepsilon_{ij} = 0$ ,  $var(\varepsilon_{ij}) = \sigma^2$ , and the number of observations,  $N_i(n)$  depending on the sample size  $n$ , are considered random. We make the following assumption,

- (A1.1) The number of observations  $N_i(n)$  made for the  $i$ th subject or cluster,  $i = 1, \dots, n$ , is a random variable with  $N_i(n) \stackrel{i.i.d.}{\sim} N(n)$ , where  $N(n) > 0$  is a positive integer valued random variable with  $\lim_{n \rightarrow \infty} P_{n \rightarrow \infty} EN(n)^2/[EN(n)]^2 < \infty$  and  $\lim_{n \rightarrow \infty} P_{n \rightarrow \infty} EN(n)^4/[EN(n)]^3 < \infty$ .

In the sequel the dependence of  $N_i(n)$  and  $N(n)$  on the sample size  $n$  is suppressed for implicit; i.e.,  $N_i = N_i(n)$  and  $N(n) = N$ . The observation time and measurement are assumed to be independent of the number of measurements, i.e., for any subset  $J_i \subseteq \{1, \dots, N_i\}$  and for all  $i = 1, \dots, n$ ,

- (A1.2)  $(\{T_{ij} : j \in J_i\}, \{Y_{ij} : j \in J_i\})$  is independent of  $N_i$ .  
 Writing  $\mathbf{T}_i = (T_{i1}, \dots, T_{iN_i})^T$  and  $\mathbf{Y}_i = (Y_{i1}, \dots, Y_{iN_i})^T$ , it is easy to see that the triple  $\{\mathbf{T}_i, \mathbf{Y}_i, N_i\}$  are i.i.d..

### 2.1. Asymptotic normality of one-dimensional smoother

To assume appropriate regularity condition that are needed to derive asymptotic properties, we define a new type of continuity that differs from those which are commonly used. We say that a real function  $f(x, y) : \mathfrak{R}^{p+q} \rightarrow \mathfrak{R}$  is continuous on  $x \in A \subseteq \mathfrak{R}^p$  uniform in  $y \in \mathfrak{R}^q$ , provided that for any  $x \in A$  and  $\varepsilon > 0$ , there exists a neighborhood of  $x$  not depending on  $y$ , say  $U(x) \subseteq \mathfrak{R}^p$ , such that  $|f(x', y) - f(x, y)| < \varepsilon$  for all  $x' \in U(x)$  and  $y \in \mathfrak{R}^q$ .

For random design,  $(T_{ij}, Y_{ij})$  are assumed to have the identical distribution as  $(T, Y)$  with joint density  $g(t, y)$ . Assume that the observation times  $T_{ij}$  are i.i.d. with the marginal density  $f(t)$ , but dependence is allowed among  $Y_{ij}$  and  $Y_{ik}$  that are observations made for the same subject or cluster. Also denote the joint density of  $(T_j, T_k, Y_j, Y_k)$  by  $g_2(t_1, t_2, y_1, y_2)$ , where  $j \neq k$ . Let  $v, k$  be given integers, with  $0 \leq v < k$ . We assume regularity condition for the marginal and joint densities,  $f(t)$ ,  $g(t, y)$ ,  $g_2(t_1, t_2, y_1, y_2)$  and the mean function of the underlying process  $X(t)$ , i.e.,  $E[X(t)] = \mu(t)$ , with respect to a neighborhood of an interior point  $t \in \mathcal{T}$ , assuming that there exists a neighborhood  $U(t)$  of  $t$  such that:

- (B1.1)  $\frac{d^k}{du^k} f(u)$  exists and is continuous on  $u \in U(t)$ , and  $f(u) > 0$  for  $u \in U(t)$ ;  
 (B1.2)  $g(u, y)$  is continuous on  $u \in U(t)$  uniform in  $y \in \mathfrak{R}$ ;  $\frac{d^k}{du^k} g(u, y)$  exists and is continuous on  $u \in U(t)$  uniform in  $y \in \mathfrak{R}$ ;  
 (B1.3)  $g_2(u, v, y_1, y_2)$  is continuous on  $(u, v) \in U(t)^2$  uniform in  $(y_1, y_2) \in \mathfrak{R}^2$ ;  
 (B1.4)  $\frac{d^k}{du^k} \mu(u)$  exists and is continuous on  $u \in U(t)$ .

Let  $K_1(\cdot)$  be nonnegative bivariate kernel function in one-dimensional smoothing. The assumption for kernel  $K_1 : \mathfrak{R} \rightarrow \mathfrak{R}$  are as follows. We say that a bivariate kernel function  $K_1$  is of order  $(v, k)$ , if

$$\int u^\ell K_1(u) du = \begin{cases} 0, & 0 \leq \ell < k, \ell \neq v, \\ (-1)^v v!, & \ell = v, \\ \neq 0, & \ell = k, \end{cases} \tag{2}$$

- (B2.1)  $K_1$  is compactly supported,  $\|K_1\|^2 = \int K_1^2(u) du < \infty$ ;
- (B2.2)  $K_1$  is a kernel function of order  $(v, \ell)$ .

Let  $b = b(n)$  be a sequence of bandwidths that are used in one-dimensional smoothing. We develop asymptotic as  $n \rightarrow \infty$ , and require

- (B3)  $b \rightarrow 0, n(EN)b^{v+1} \rightarrow \infty, b(EN) \rightarrow 0$ , and  $n(EN)b^{2k+1} \rightarrow d^2$  for some  $d$  with  $0 \leq d < \infty$ .

One could see in the proof of Theorem 1 that the assumption (B3) combined with (A1.1) provide the condition such that the local properties of kernel-type estimator hold for longitudinal or functional data with the presence of within-subject correlation.

Let  $\{\psi_\lambda\}_{\lambda=1, \dots, l}$  be a collection of real function  $\psi_\lambda : \mathbb{R}^2 \rightarrow \mathbb{R}$ , which satisfy:

- (B4.1)  $\psi_\lambda(t, y)$  are continuous on  $\{t\}$  uniformly in  $y \in \mathbb{R}$ ;
- (B4.2)  $\frac{d^k}{dt^k} \psi_\lambda(t, y)$  exist for all argument  $(t, y)$  and are continuous on  $\{t\}$  uniformly in  $y \in \mathbb{R}$ .

Then we define the general weighted average

$$\Psi_{\lambda n} = \frac{1}{nENb^{v+1}} \sum_{i=1}^n \sum_{j=1}^{N_i} \psi_\lambda(T_{ij}, Y_{ij}) K_1\left(\frac{t - T_{ij}}{b}\right), \quad \lambda = 1, \dots, l.$$

and

$$\mu_\lambda = \mu_\lambda(t) = \frac{d^v}{dt^v} \int \psi_\lambda(t, y) g(t, y) dy, \quad \lambda = 1, \dots, l.$$

Let

$$\sigma_{\kappa\lambda} = \sigma_{\kappa\lambda}(t) = \int \psi_\kappa(t, y) \psi_\lambda(t, y) g(t, y) dy \|K_1\|^2, \quad 1 \leq \lambda, \kappa \leq l,$$

and  $H : \mathbb{R}^l \rightarrow \mathbb{R}$  be a function with continuous first order derivatives. We denote the gradient vector  $((\partial H / \partial x_1)(v), \dots, (\partial H / \partial x_l)(v))^T$  by  $DH(v)$  and  $\bar{N} = \sum_{i=1}^n N_i/n$ .

**Theorem 1.** *If the assumptions (A1.1), (A1.2) and (B1.1)–(B4.2) hold, then*

$$\sqrt{n\bar{N}b^{2v+1}} [H(\Psi_{1n}, \dots, \Psi_{ln}) - H(\mu_1, \dots, \mu_l)] \xrightarrow{\mathcal{D}} \mathcal{N}(\beta, [DH(\mu_1, \dots, \mu_l)]^T \Sigma [DH(\mu_1, \dots, \mu_l)]), \tag{3}$$

where

$$\beta = \frac{(-1)^k d}{k!} \int u^k K_1(u) du \sum_{\lambda=1}^l \frac{\partial H}{\partial \mu_\lambda} \{(\mu_1, \dots, \mu_l)^T\} \frac{d^{k-v}}{dt^{k-v}} \mu_\lambda(t), \quad \Sigma = (\sigma_{\kappa\lambda})_{1 \leq \kappa, \lambda \leq l}.$$

**Proof.** It is seen that  $\bar{N}$  can be replaced with  $EN$  by Slutsky Theorem under (A1.1). We now have that

$$\sqrt{n(EN)b^{2v+1}} [H(E\Psi_{1n}, \dots, E\Psi_{ln}) - H(\mu_1, \dots, \mu_l)] \rightarrow \beta. \tag{4}$$

Since (A1.1) and (A1.2) hold, and  $K_1$  is of order  $(v, k)$ , using Taylor expansion to order  $k$ , one obtain

$$\begin{aligned}
 E\Psi_{\lambda n} &= \frac{1}{nb^{v+1}} E \left\{ \sum_{i=1}^n \frac{1}{EN} \sum_{j=1}^{N_i} \psi_{\lambda}(T_{ij}, Y_{ij}) K_1 \left( \frac{t - T_{ij}}{b} \right) \right\} \\
 &= \frac{1}{b^{v+1} EN} E \left\{ \sum_{j=1}^N E \left[ \psi_{\lambda}(T_j, Y_j) K_1 \left( \frac{t - T_j}{b} \right) \middle| N \right] \right\} \\
 &= \frac{1}{b^{v+1}} E \left\{ \psi_{\lambda}(T, Y) K_1 \left( \frac{t - T}{b} \right) \right\} \\
 &= \mu_{\lambda} + \frac{(-1)^k}{k!} \int u^k K_1(u) du \frac{d^{k-v}}{dt^{k-v}} \mu_{\lambda}(t) b^{k-v} + o(b^{k-v}). \tag{5}
 \end{aligned}$$

Then (4) follows from an  $l$ -dimensional Taylor expansion of  $H$  of order 1 around  $(\mu_1, \dots, \mu_l)^T$ , combined with (5). If we can show

$$\sqrt{n(EN)b^{2v+1}} [(\Psi_{1n}, \dots, \Psi_{ln})^T - (E\Psi, \dots, E\Psi_{ln})^T] \xrightarrow{\mathcal{D}} \mathcal{N}(0, \Sigma), \tag{6}$$

in analogy to Bhattacharya and Mallik [1], and continue of  $DH$  at  $(\mu_1, \dots, \mu_l)^T$  and applying similar argument as in (5), we find  $DH(E\Psi_{1n}, \dots, E\Psi_{ln}) \rightarrow DH(\mu_1, \dots, \mu_l)$ . Then Cameron-Wold decision field

$$\begin{aligned}
 &\sqrt{n(EN)b^{2v+1}} [H(\Psi_{1n}, \dots, \Psi_{ln}) - H(E\Psi, \dots, E\Psi_{ln})] \xrightarrow{\mathcal{D}} \mathcal{N}(0, DH(\mu_1, \dots, \mu_l)^T \\
 &\quad \Sigma DH(\mu_1, \dots, \mu_l)), \tag{7}
 \end{aligned}$$

combined with (4), leading to (3).

It remains to show (6). Observe that (A1.1) and (A1.2), one has

$$\begin{aligned}
 &n(EN)b^{2v+1} \text{cov}(\Psi_{\lambda n}, \Psi_{\kappa n}) \\
 &= \frac{1}{b} E \left\{ \frac{1}{EN} \left[ \sum_{j=1}^N \psi_{\lambda}(T_j, Y_j) K_1 \left( \frac{t - T_j}{b} \right) \right] \left[ \sum_{k=1}^N \psi_{\kappa}(T_k, Y_k) K_1 \left( \frac{t - T_k}{b} \right) \right] \right\} \\
 &\quad - \frac{EN}{b} E \left[ \frac{1}{EN} \sum_{j=1}^N \psi_{\lambda}(T_j, Y_j) K_1 \left( \frac{t - T_j}{b} \right) \right] \\
 &\quad \times E \left[ \frac{1}{EN} \sum_{k=1}^N \psi_{\kappa}(T_k, Y_k) K_1 \left( \frac{t - T_k}{b} \right) \right] \\
 &\equiv I_1 - I_2.
 \end{aligned}$$

It is obvious that  $I_2 = O(b) = o(1)$  from the definition of (5). For  $I_1$ , it can be written as

$$\begin{aligned}
 I_1 &= \frac{1}{b} E \left[ \frac{1}{EN} \sum_{j=1}^N \psi_\lambda(T_j, Y_j) \psi_\kappa(T_j, Y_j) K_1^2 \left( \frac{t - T_j}{b} \right) \right] \\
 &\quad + \frac{1}{b} E \left[ \frac{1}{EN} \sum_{1 \leq j \neq k \leq N} \psi_\lambda(T_j, Y_j) \psi_\kappa(T_k, Y_k) K_1 \left( \frac{t - T_j}{b} \right) K_1 \left( \frac{t - Y_k}{b} \right) \right] \\
 &\equiv Q_1 + Q_2.
 \end{aligned}$$

Applying (A1.1) and (A1.2), one has

$$\begin{aligned}
 Q_1 &= \frac{1}{b} E \left\{ \frac{1}{EN} \sum_{j=1}^N E \left[ \psi_\lambda(T_j, Y_j) \psi_\kappa(T_j, Y_j) K_1^2 \left( \frac{t - T_j}{b} \right) \middle| N \right] \right\} \\
 &= \frac{1}{b} E \left[ \psi_\lambda(T, Y) \psi_\kappa(T, Y) K_1^2 \left( \frac{t - Y}{b} \right) \right] = \sigma_{\lambda\kappa} + o(1).
 \end{aligned}$$

Then (4) will hold, observing (A1.1) and the following argument that guarantees the local property of the kernel-based estimator with the presence of within-subject correlation in longitudinal or functional data,

$$\begin{aligned}
 Q_2 &= \frac{1}{bEN} E \left\{ \sum_{1 \leq j \neq k \leq N} E \left[ \psi_\lambda(T_j, Y_j) \psi_\kappa(T_k, Y_k) K_1 \left( \frac{t - T_j}{b} \right) K_1 \left( \frac{t - T_k}{b} \right) \middle| N \right] \right\} \\
 &= \frac{EN(N-1)}{bEN} E \left[ \psi_\lambda(T_1, Y_1) \psi_\kappa(T_2, Y_2) K_1 \left( \frac{t - T_1}{b} \right) K_1 \left( \frac{t - T_2}{b} \right) \right] \\
 &= \frac{bEN(N-1)}{EN} \int_{\mathbb{R}^4} \psi_\lambda(t - ub, y_1) \psi_\kappa(t - vb, y_2) K_1(u) K_2(v) \\
 &\quad \times g_2(t - ub, t - vb, y_1, y_2) du dv dy_1 dy_2 \\
 &= \frac{bEN(N-1)}{EN} \int_{\mathbb{R}^2} \psi_\lambda(t, y_1) \psi_\kappa(t, y_2) g_2(t, t, y_1, y_2) dy_1 dy_2 + o(b) = o(1),
 \end{aligned}$$

i.e., the within-subject correlation can be ignored while deriving the asymptotic variance.  $\square$

### 2.2. Asymptotic normality of two-dimensional smoother

The general asymptotic result can be extended to  $d$ -dimensional smoothing. Let  $(\mathbf{v}, \mathbf{k})$  denote the multi-indices  $\mathbf{v} = (v_1, v_2)$  and  $\mathbf{k} = (k_1, k_2)$ , here  $|\mathbf{v}| = v_1 + v_2$  and  $|\mathbf{k}| = k_1 + k_2$ . In  $d$ -dimensional smoothing, more regularity assumptions are needed for joint density. Let  $f_2(s, t)$  be the joint density of  $(T_j, T_k)$ , and  $g_4(s, t, s', t', y_1, y_2, y'_1, y'_2)$  the joint density of  $(T_j, T_k, T_{j'}, T_{k'}, Y_j, Y_k, Y_{j'}, Y_{k'})$ , here  $j \neq k, (j, k) \neq (j', k')$ . Denote the covariance surface  $C(s, t) = \text{cov}(X(T_j), X(T_k) | T_j = s, T_k = t)$ . The following regularity conditions are assumed, here  $U(s, t)$  is some neighborhood of  $\{(s, t)\}$ ,

$$\text{(C1.1)} \quad \frac{d^{|\mathbf{k}|}}{du^{k_1} dv^{k_2}} f_2(u, v) \text{ is continuous on } (u, v) \in U(s, t), \text{ and } f_2(u, v) > 0 \text{ for } (u, v) \in U(s, t);$$

- (C1.2)  $g_2(u, v, y_1, y_2)$  is continuous on  $(u, v) \in U(s, t)$ , nonrandom in  $(y_1, y_2) \in \mathfrak{R}^2$ ;  $\frac{d^{|k|}}{du^{k_1} dv^{k_2}} g_2(u, v, y_1, y_2)$  is continuous on  $(u, v) \in U(s, t)$ , nonrandom in  $(y_1, y_2) \in \mathfrak{R}^2$ ;
- (C1.3)  $g_4(u, v, u', v', y_1, y_2, y'_1, y'_2)$  is continuous on  $(u, v, u', v') \in U(s, t)^2$ , nonrandom in  $(y_1, y_2, y'_1, y'_2) \in \mathfrak{R}^4$ ;
- (C1.4)  $\frac{d^{|k|}}{du^{k_1} dv^{k_2}} C(u, v)$  is continuous on  $(u, v) \in U(s, t)$ .

Let  $K_2$  be nonnegative bivariate kernel function defined in the  $\nu$ -dimensional smoothing. The assumption for kernel  $K_2$  are as follows,

- (C2.1)  $K_2$  is compactly supported  $\nu$  with  $\|K_2\|^2 = \int_{\mathfrak{R}^2} K_2^2(u, v) du dv < \infty$ , and is symmetric with respect to coordinate  $u$  and  $v$ .
- (C2.2)  $K_2$  is a kernel function of order  $(|v|, |k|)$ , i.e.,

$$\sum_{\ell_1 + \ell_2 = |l|} \int_{\mathfrak{R}^2} u^{\ell_1} v^{\ell_2} K_2(u, v) du dv = \begin{cases} 0, & 0 \leq |l| < |k|, |l| \neq |v|, \\ (-1)^{|v||v|!}, & |l| = |v|, \\ \neq 0, & |l| = |k|. \end{cases} \tag{8}$$

Let  $h = h(n)$  be a sequence of bandwidth defined in  $\nu$ -dimensional smoothing, while it is possible that the bandwidth defined for  $\nu$  argument may be different. Since we are still focus on the estimator of the covariance surface that is symmetric about the diagonal, it is sufficient to consider the identical bandwidth for the  $\nu$  argument. The asymptotic developed as  $n \rightarrow \infty$  as follows:

- (C3)  $h \rightarrow 0, nEN^2h^{|v|+2} \rightarrow \infty, hEN^3 \rightarrow 0$ , and  $nE[N(N-1)]h^{2|k|+2} \rightarrow e^2$  for some  $0 \leq e < \infty$ .

Similar to the one-dimensional smoothing case, assumption (C3) and (A1.1) guarantee the local property of the bivariate kernel-based estimator with the presence of within-subject correlation.

Let  $\{\phi_\lambda\}_{\lambda=1, \dots, l}$  be a collection of real function  $\phi_\lambda: \mathfrak{R}^4 \rightarrow \mathfrak{R}, \lambda = 1, \dots, l$ , satisfying

- (C4.1)  $\phi_\lambda(s, t, y_1, y_2)$  are continuous on  $\{(s, t)\}$ , nonrandom in  $(y_1, y_2) \in \mathfrak{R}^2$ ;
- (C4.2)  $\frac{d^{|k|}}{ds^{k_1} dt^{k_2}} \phi_\lambda(s, t, y_1, y_2)$  is continuous for all argument  $(s, t, y_1, y_2)$  and are continuous on  $\{(s, t)\}$ , nonrandom in  $(y_1, y_2) \in \mathfrak{R}^2$ .

Then the general  $\nu$ -eighted average of  $\nu$ -dimensional smoothing are defined below, for  $1 \leq \lambda \leq l$ ,

$$\begin{aligned} \Phi_{\lambda n} = \Phi_{\lambda n}(t, s) &= \frac{1}{nE[N(N-1)]h^{|v|+2}} \sum_{i=1}^n \sum_{1 \leq j \neq k \leq N_i} \phi_\lambda(T_{ij}, T_{ik}, Y_{ij}, Y_{ik}) \\ &\times K_2\left(\frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h}\right). \end{aligned}$$

Let

$$m_\lambda = m_\lambda(s, t) = \sum_{v_1 + v_2 = |v|} \frac{d^{|v|}}{ds^{v_1} dt^{v_2}} \int_{\mathfrak{R}^2} \phi_\lambda(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2, \quad 1 \leq \lambda \leq l,$$



and

$$\omega_{\kappa\lambda} = \omega_{\kappa\lambda}(s, t) = \int_{\mathfrak{M}^2} \phi_{\kappa}(s, t, y_1, y_2) \phi_{\lambda}(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2 \|K_2\|^2,$$

$$1 \leq \kappa, \lambda \leq l,$$

and  $H : \mathfrak{M}^l \rightarrow \mathfrak{R}$  is a function with continuous first order derivatives a priori defined.

**Theorem 2.** *If assumptions (A1.1), (A1.2) and (C1.1)–(C4.2) hold, then*

$$\begin{aligned} & \sqrt{n\bar{N}(\bar{N} - 1)h^{2|v|+2}} [H(\Phi_{1n}, \dots, \Phi_{ln}) - H(m_1, \dots, m_l)] \\ & \xrightarrow{\mathcal{D}} \mathcal{N}(\gamma, [DH(m_1, \dots, m_l)]^T \Omega [DH(m_1, \dots, m_l)]), \end{aligned} \tag{9}$$

where

$$\begin{aligned} \gamma &= \frac{(-1)^{|k|} e}{|k|!} \sum_{\lambda=1}^l \left\{ \sum_{k_1+k_2=|k|} \int_{\mathfrak{M}^2} u^{k_1} v^{k_2} K_2(u, v) du dv \frac{d^{|k|}}{ds^{k_1} dt^{k_2}} \right. \\ & \quad \left. \times \int_{\mathfrak{M}^2} \phi_{\lambda}(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2 \right\} \\ & \quad \times \left\{ \frac{\partial H}{\partial m_{\lambda}}(m_1, \dots, m_l)^T \right\}, \end{aligned}$$

$$\Omega = (\omega_{\kappa\lambda})_{1 \leq \kappa \leq l}.$$

The proof of Theorem 2 essentially follows that of Theorem 1 with appropriate modification which are required for  $\mathfrak{M}^l$ -dimensional smoothing.

### 3. Applications to nonparametric regression estimators for functional or longitudinal data

Although various version of kernel-based estimator have been introduced in literature, Nadaraya-Watson and local polynomial, especially local linear estimator, are the most commonly used non-parametric smoothing technique in longitudinal or functional data analysis. Despite their inherent subject correlation, the asymptotic behavior in terms of bias and variance of the estimator for nonindependent longitudinal or functional data have not been a well understood as for i.i.d. data. Especially, asymptotic result for covariance estimator do not exist. Therefore in this section, we apply the asymptotic result developed for general functional to Nadaraya-Watson and local linear estimator of regression function and covariance surface to obtain their asymptotic distribution.

#### 3.1. Asymptotic distributions of mean estimators

We apply Theorem 1 to the local asymptotic distribution of the commonly used Nadaraya-Watson kernel estimator  $\hat{\mu}_N(t)$  and local linear estimator  $\hat{\mu}_L(t)$  for functional/longitudinal

data:

$$\hat{\mu}_N(t) = \left[ \sum_{i=1}^n \sum_{j=1}^{N_i} K_1 \left( \frac{t - T_{ij}}{b} \right) Y_{ij} \right] / \left[ \sum_{i=1}^n \sum_{j=1}^{N_i} K_1 \left( \frac{t - T_{ij}}{b} \right) \right], \tag{10}$$

$$\hat{\mu}_L(t) = \hat{\alpha}_0(t) = \underset{(\alpha_0, \alpha_1)}{\text{arg min}} \left\{ \sum_{i=1}^n \sum_{j=1}^{N_i} K_1 \left( \frac{t - T_{ij}}{b} \right) [Y_{ij} - (\alpha_0 + \alpha_1(T_{ij} - t))]^2 \right\}. \tag{11}$$

**Corollary 1.** *If assumptions (A1.1), (A1.2), and (B1.1)–(B3) hold with  $v = 0$  and  $k = 2$ , then*

$$\sqrt{n\bar{N}b}[\hat{\mu}_N(t) - \mu(t)] \xrightarrow{\mathcal{D}} \mathcal{N} \left( \frac{d \mu^{(2)}(t) f(t) + 2\mu^{(1)}(t) f^{(1)}(t)}{f(t)} \sigma_{K_1}^2, \frac{\text{var}(Y|T=t) \|K_1\|^2}{f(t)} \right), \tag{12}$$

where  $d$  is as in (B3),  $\sigma_{K_1}^2 = \int u^2 K_1(u) du$  and  $\|K_1\|^2 = \int K_1(u)^2 du$ .

Here  $w_{ij} = K_1((t - T_{ij})/b)/(nb)$ , where  $K_1$  is a kernel function of order  $(0, 2)$ , satisfying (B2.1) and (B2.2), and  $\hat{\alpha}_1(t)$  is an estimator for the first derivative  $\mu'(t)$  of  $\mu$  at  $t$ .

Observing that Corollary 1 implies  $\hat{\mu}_N(t) \xrightarrow{P} \mu(t)$ , let  $\hat{f}(t) = \sum_i \sum_j w_{ij}/N_i$ , it is easy to show  $\hat{f}(t) \xrightarrow{P} f(t)$  in analog to Corollary 1. We proceed to show  $\hat{\alpha}_1(t) \xrightarrow{P} \mu'(t)$ . Denote  $\sigma_{K_1}^2 = \int u^2 K_1(u) du$ , the kernel function  $\tilde{K}_1(t) = -tK_1(t)/\sigma_{K_1}^2$ , and define  $\Psi_{\lambda n}, 1 \leq \lambda \leq 3$  by  $\psi_1(u, y) = y, \psi_2(u, y) \equiv 1, \psi_3(u, y) = u - t$ . Observe that  $\tilde{K}_1$  is of order  $(1, 3)$ ,  $\hat{f}(t) \xrightarrow{P} f(t)$ , and define

$$\tilde{H}(x_1, x_2, x_3) = \frac{x_1 - x_2 \hat{\mu}_N(t)}{x_3 - bx_2^2/\hat{f}(t) \cdot \sigma_{K_1}^2} \quad \text{and} \quad H(x_1, x_2, x_3) = \frac{x_1 - x_2 \mu(t)}{x_3}.$$

Then

$$\begin{aligned} \hat{\alpha}_1(t) &= \tilde{H}(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) \\ &= \left[ H(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) + \frac{\Psi_{2n}(\mu(t) - \hat{\mu}_N(t))}{\Psi_{3n}} \right] \frac{\Psi_{3n}}{\Psi_{3n} + b^2 \Psi_{2n}^2/\hat{f}(t) \cdot \sigma_{K_1}^2}. \end{aligned}$$

Note that  $\mu_1 = (\mu'f + mf')(t), \mu_2 = f'(t)$ , and  $\mu_3 = f(t)$ , implying  $\Psi_{\lambda n} - \mu_\lambda = O_p(1/\sqrt{n\bar{N}b^3})$ , for  $\lambda = 1, 2, 3$ , by Theorem 1. Using Slutsky's Theorem,  $|\tilde{H}(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) - \mu'(t)| = O_p(1/\sqrt{n\bar{N}b^3})$  follows.

For the asymptotic distribution of  $\hat{\mu}_L$ , note that

$$\hat{\mu}_L(t) = \frac{\sum_i \frac{1}{EN} \sum_j w_{ij} Y_{ij} - \sum_i \frac{1}{EN} \sum_j w_{ij} (T_{ij} - t) \hat{\alpha}_1(t)}{\sum_i \frac{1}{EN} \sum_j w_{ij}}.$$

Considering  $\sqrt{n\bar{N}b} \sum_i \frac{1}{EN} \sum_j w_{ij} (T_{ij} - t) = \sqrt{n\bar{N}b} \sigma_{K_1}^2 b^2 \Psi_{2n}$ . Since  $\tilde{K}_1$  is of order  $(1, 3)$ , Theorem 1 implies  $\Psi_{2n} = f'(t) + O_p(1/\sqrt{n\bar{N}b^3})$ , which yields  $\sqrt{n\bar{N}b} \sigma_{K_1}^2 b^2 \Psi_{2n} = \sqrt{n\bar{N}b^5} \sigma_{K_1}^2 f'(t) + \sigma_{K_1}^2 O_p(b) = o_p(1)$  by observing  $n\bar{N}b^5 \rightarrow d^2$  for  $0 \leq d < \infty$ . Since  $\hat{f}(t) \xrightarrow{P} f(t)$  and  $|\hat{\alpha}_1(t) - \mu'(t)| = O_p(1/\sqrt{n\bar{N}b^3}) = o_p(1)$ , we find

$$\begin{aligned} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}b} [\hat{\mu}_L(t) - \mu(t)] &\stackrel{D}{=} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}b} \\ &\times \left\{ \frac{\sum_i \frac{1}{EN} \sum_j w_{ij} Y_{ij} - \mu'(t) \sum_i \frac{1}{EN} \sum_j w_{ij} T_{ij} + t \mu'(t) \sum_i \frac{1}{EN} \sum_j w_{ij}}{\sum_i \frac{1}{EN} \sum_j w_{ij}} - \mu(t) \right\}. \end{aligned}$$

Using the kernel  $K_1$  of order  $(0, 2)$ , we re-define  $\Psi_{\lambda n}, 1 \leq \lambda \leq 3$ , though  $\psi_1(u, y) = y, \psi_2(u, y) = u$  and  $\psi_3(u, y) \equiv 1$ , letting  $v = 0, k = 2, l = 3$  and  $H(x_1, x_2, x_3) = [x_1 - \mu'(t)x_2 + t\mu'(t)x_3]/x_3$ . Then (13) follows by applying Theorem 1.  $\square$

### 3.2. Asymptotic distributions of covariance estimators

Note that in model (1),  $cov(Y_{ij}, Y_{ik}|T_{ij}, T_{ik}) = cov(X(T_{ij}), X(T_{ik})) + \sigma^2 \delta_{jk}$ , where  $\delta_{jl} = 1$  if  $j = k$  and 0 otherwise. Let  $C_{ijk} = (Y_{ij} - \hat{\mu}(T_{ij}))(Y_{ik} - \hat{\mu}(T_{ik}))$  be the covariance, where  $\hat{\mu}(t)$  is the estimated mean function obtained from the previous step, for instance,  $\hat{\mu}(t) = \hat{\mu}_N(t)$  or  $\hat{\mu}(t) = \hat{\mu}_L(t)$ . It is easy to see that  $E[C_{ijk}|T_{ij}, T_{ik}] \approx cov(X(T_{ij}), X(T_{ik})) + \sigma^2 \delta_{jk}$ . Therefore,

the diagonal of the  $\Sigma_{\mathbf{X}}$  covariance should be removed, i.e., only  $C_{ijk}, j \neq k$ , should be included as input data for the covariance surface smoothing step, as previously observed in Stanifani and Lee [12] and Yao et al. [15].

Commonly used nonparametric regression estimator of the covariance surface,  $C(s, t) = E\{[X(T_1) - \mu(T_1)][X(T_2) - \mu(T_2)] | T_1 = s, T_2 = t\}$ , are the  $d_{\mathbf{X}}$ -dimensional Nadaraya-Watson estimator and local linear estimator defined as follows:

$$\begin{aligned} \widehat{C}_N(s, t) &= \left[ \sum_{i=1}^n \sum_{j \neq k} K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right) C_{ijk} \right] / \\ &\quad \left[ \sum_{i=1}^n \sum_{j \neq k} K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right) \right], \\ \widehat{C}_L(s, t) &= \widehat{\beta}_0(s, t) = \arg \min_{\beta} \left\{ \sum_{i=1}^n \sum_{j \neq k} K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right) \right. \\ &\quad \left. \times [C_{ijk} - f(\beta, (s, t), (T_{ij}, T_{ik})))]^2 \right\} \end{aligned} \tag{16}$$

$\phi_1(t_1, t_2, y_1, y_2) = (y_1 - \mu(t_1))(y_2 - \mu(t_2))$ ,  $\phi_2(t_1, t_2, y_1, y_2) = y_1 - \mu(t_1)$ , and  $\phi_3(t_1, t_2, y_1, y_2) \equiv 1$ , then  $\int_{\mathcal{P}_{t,s \in \mathcal{T}}} |\Phi_{pm}| = O_p(1)$ , for  $p = 1, 2, 3$ , by Lemma 1 of Yao et al. [16]. This implies that  $\int_{\mathcal{P}_{t,s \in \mathcal{T}}} |\Phi_{2n}| O_p(1/(\sqrt{nb})) = O_p(1/(\sqrt{nb}))$  and  $\int_{\mathcal{P}_{t,s \in \mathcal{T}}} |\Phi_{3n}| O_p(1/(\sqrt{nb})) = O_p(1/(\sqrt{nb}))$ . Since  $\int_{\mathcal{P}_{t \in \mathcal{T}}} |\hat{\mu}(t) - \mu(t)|^2 = O_p(1/(nb))$  are negligible compared to  $\Phi_{1n}$ , the Nadaraya-Watson estimator  $\tilde{C}_N(s, t)$ , of  $C(s, t)$  obtained from  $C_{ijk}$  is asymptotically equivalent to that obtained from  $\tilde{C}_{ijk}$ , denoted by  $\tilde{C}_N(t, s)$ .

Therefore, it is sufficient to show that the asymptotic distribution of  $\tilde{C}_N(s, t)$  follows (18). Choose  $v = (0, 0)$ ,  $|k| = 2$ ,  $\phi_1(s, t, y_1, y_2) = (y_1 - \mu(s))(y_2 - \mu(t))$ ,  $\phi_2(s, t, y_1, y_2) \equiv 1$  and  $H(x_1, x_2) = x_1/x_2$  in Theorem 2, then  $\tilde{C}_N(s, t) = H(\Psi_{1n}, \Psi_{2n})$ . To compute  $\gamma_N(s, t)$ , we have  $DH(m_1, m_2) = (1/m_2, -m_1/m_2^2)$ , and note  $m_1(s, t) = \int_{\mathbb{R}^2} (y_1 - \mu(s))(y_2 - \mu(t))g_2(s, t, y_1, y_2) dy_1 dy_2 = f_2(s, t)C(s, t)$  and  $m_2(s, t) = f_2(s, t)$ . One has  $(d^2/dt^2)m_1(s, t) = [(d^2 f_2/dt^2)C + 2(df_2/dt)(dC/dt) + f_2(d^2 C/dt^2)](s, t)$ ,  $(d^2/dt^2)m_2(s, t) = d^2 f_2(s, t)/dt^2$  and similarly with respect to the argument  $s$  leading to the bias term in (12). For the asymptotic variance, note that  $\omega_{11} = \|K_2\|^2 \int_{\mathbb{R}^2} (y_1 - \mu(s))^2 (y_2 - \mu(t))^2 g_2(s, t, y_1, y_2) dy_1 dy_2 = E[(Y_1 - \mu(T_1))^2 (Y_2 - \mu(T_2))^2 | T_1 = s, T_2 = t] f_2(s, t) \|K_2\|^2$ ,  $\omega_{12} = \omega_{21} = \|K_2\|^2 f_2(s, t) C(s, t)$ ,  $\omega_{22} = \|K_2\|^2 f_2(s, t)$ , and  $DH(m_1, m_2) = (1/m_2, -m_1/m_2^2)$ , yielding the variance term in (12).  $\square$

**Corollary 4.** *If the assumptions (A1.1), (A1.2), and (C1.1)–(C3) hold with  $|v| = 0$  and  $|k| = 2$ , then*

$$\sqrt{n\bar{N}(\bar{N} - 1)h^2} [\hat{C}_L(s, t) - C(s, t)] \xrightarrow{D} \mathcal{N} \left( \frac{e}{4} \sigma_{K_2}^2 [d^2 C(s, t)/ds^2 + d^2 C(s, t)/dt^2], \frac{v(s, t) \|K_2\|^2}{f_2(s, t)} \right), \tag{19}$$

where  $e$  is as in (C3),  $v(s, t) = \text{var}\{(Y_1 - \mu(T_1))(Y_2 - \mu(T_2)) | T_1 = s, T_2 = t\}$ ,  $\sigma_{K_2}^2 = \int_{\mathbb{R}^2} (u^2 + v^2) K_2(u, v) du dv$ ,  $\|K_2\|^2 = \int_{\mathcal{R}^2} K_2^2(u, v) du dv$ .

**Proof.** In analogy to the proof of Corollary 3, the local linear estimator  $\hat{C}_L(s, t)$  obtained from  $C_{ijk}$  is asymptotically equivalent to that obtained from  $\tilde{C}_{ijk}$ , denoted by  $\tilde{C}_L(t, s)$ . Also denote the solution to (17), after substituting  $\tilde{C}_{ijk}$  for  $C_{ijk}$ , by  $\tilde{\beta}(s, t) = (\tilde{\beta}_0(s, t), \tilde{\beta}_1(s, t), \tilde{\beta}_2(s, t))$ , and in fact  $\tilde{\beta}_0(s, t) = \tilde{C}_L(s, t)$ . For simplicity, let  $W_{ijk} = K_2((s - T_{ij})/h, (t - T_{ik})/h)/(nh^2)$  and  $\sum_{i,j \neq k}$  "abbreviation of  $\sum_{i=1}^n \sum_{j \neq k}$ ". Algebraic calculation yields that

$$\begin{aligned} \tilde{C}_L &= \frac{\sum_{i,j \neq k} \tilde{C}_{ijk} W_{ijk} - \tilde{\beta}_1 \sum_{i,j \neq k} W_{ijk} T_{ij} + \tilde{\beta}_1 \sum_{i,j \neq k} W_{ijk} s - \tilde{\beta}_2 \sum_{i,j \neq k} W_{ijk} T_{ik} + \tilde{\beta}_2 \sum_{i,j \neq k} W_{ijk} t}{\sum_{i,j \neq k} W_{ijk}}, \\ \tilde{\beta}_1 &= \frac{R_{00}(S_{10}S_{02} - S_{01}S_{11}) + R_{10}(S_{00}S_{02} - S_{01}S_{20}) - R_{01}(S_{00}S_{11} - S_{10}S_{02})}{S_{00}S_{20}S_{02} - S_{00}S_{11}^2 - S_{10}^2S_{02} + S_{10}S_{01}S_{11} + S_{20}S_{10}S_{11} - S_{01}S_{20}^2}, \\ \tilde{\beta}_2 &= \frac{R_{00}(S_{10}S_{11} - S_{01}S_{02}) - R_{10}(S_{00}S_{11} - S_{01}S_{20}) + R_{01}(S_{00}S_{20} - S_{10}^2)}{S_{00}S_{20}S_{02} - S_{00}S_{11}^2 - S_{10}^2S_{02} + S_{10}S_{01}S_{11} + S_{20}S_{10}S_{11} - S_{01}S_{20}^2}, \end{aligned}$$

where

$$R_{pq} = \sum_{i,j \neq k} W_{ijk} (T_{ij} - s)^p (T_{ik} - t)^q \tilde{C}_{ijk}, \quad S_{pq} = \sum_{i,j \neq k} W_{ijk} (T_{ij} - s)^p (T_{ik} - t)^q.$$

Note that  $\tilde{\beta}_1$  and  $\tilde{\beta}_2$  are local linear estimators of the partial derivative of  $C(s, t)$ ,  $dC(s, t)/ds$  and  $dC(s, t)/dt$ , respectively. In analogy to the proof of Corollary 2, it can be shown that  $|\tilde{\beta}_1(s, t) - dC(s, t)/ds| = O_p(1/\sqrt{nEN(N-1)h^4})$  and  $|\tilde{\beta}_2(s, t) - dC(s, t)/dt| = O_p(1/\sqrt{n\bar{N}(\bar{N}-1)h^4})$  by applying Theorem 2. Then one can substitute  $dC(s, t)/ds, dC(s, t)/dt$  for  $\tilde{\beta}_1(s, t), \tilde{\beta}_2(s, t)$  in  $\tilde{C}_L(s, t)$ , and denote the resulting estimator by  $C_L^*(s, t)$ . It is easy to see that

$$\lim_{n \rightarrow \infty} \sqrt{n\bar{N}(\bar{N}-1)h^2} [C_L(s, t) - C(s, t)] \stackrel{\mathcal{D}}{=} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}(\bar{N}-1)h^2} [C_L^*(s, t) - C(s, t)].$$

We define  $\Phi_{\lambda n}, 1 \leq \lambda \leq 4$ , through  $\phi_1(s, t, y_1, y_2) = (y_1 - \mu(s))(y_2 - \mu(t)), \phi_2(s, t, y_1, y_2),$

the  $e$  in Corollarie 3 and 4, with  $f(t)$  replaced by  $1/|T|$  and  $f(s, t)$  replaced by  $1/|T|^2$ , here  $|T|$  is the length of the interval.

**5. Simulation study**

An numerical study is conducted to evaluate the derived asymptotic properties. The key finding in this paper is that the asymptotic results for functional or longitudinal are comparable to those obtained from independent data, i.e., the influence of within-subject covariance does not play a significant role in determining the asymptotic bias and variance. For implicit, we focus on the local polynomial mean estimator which are often superior to the Nadaraya-Watson estimator.

We first generated  $M = 200$  sample consisting of  $n = 50$  i.i.d. random trajectories each. Following model (1), the simulated process has a mean function  $\mu(t) = (t - 1/2)^2$ ,  $0 \leq t \leq 1$  which has a constant second derivative  $\mu^{(2)}(t) = 2$ , and a constant within-subject covariance function derived from a random intercept  $\xi_1 \stackrel{i.i.d.}{\sim} N(0, \lambda_1)$ , here  $\lambda_1 = 0.01$  and  $\phi_1(t) = 1$ ,  $0 \leq t \leq 1$ . The measurement error in (1) are  $\varepsilon_{ij} \stackrel{i.i.d.}{\sim} N(0, \sigma^2)$ , here  $\sigma^2 = 0.01$ . A random design is used, here the number of observation for each subject  $N_i$  are chosen from  $\{2, 3, 4, 5\}$  with equal likelihood and the location of the observation are uniformly distributed on  $[0, 1]$ , i.e.,  $T_{ij} \stackrel{i.i.d.}{\sim} U[0, 1]$ . For comparison, we generated  $M = 200$  sample of  $n = 50$  i.i.d. random trajectories which have the same structure as in model (1) but no within-subject correlation. Letting  $\xi_{i1} = 0$  and  $\varepsilon_{ij} \stackrel{i.i.d.}{\sim} N(0, \sqrt{\lambda_1 + \sigma^2})$  lead to independent data with the same mean and variance function. Therefore, the quality of data has the same asymptotic distribution for the local polynomial mean estimator. We also generated  $M = 200$  correlated and independent sample, respectively, consisting of  $n = 200$  trajectories each for demonstrating the asymptotic behavior with the increasing sample size  $n$ .

Here we use the Epanechnikov kernel function, i.e.,  $K_1(u) = 3/4(1 - u^2)\mathbf{1}_{[-1,1]}(u)$ , here  $\mathbf{1}_A(u) = 1$  if  $u \in A$  and 0 otherwise for an set  $A$ . Note that  $n(EN)b^{2k+1} \rightarrow d^2$  in (B3),  $\mu^{(2)}(t) = 2$ ,  $var(Y|T = t) = \lambda_1 + \sigma^2 = 0.02$ , and the design density  $f(t) = 1$ , here  $k = 2$  for local polynomial estimator and  $b$  is the bandwidth used for the mean estimation. From the above construction, one can calculate the asymptotic bias and variance of the local polynomial mean estimator  $\mu_L(t)$  using Corollary 2, which is in fact applicable for both correlated and independent data. Since the bias and variance term are both constant in our simulation framework, for convenience we compare the asymptotic integrated squared bias and variance with the empirical integrated squared bias and variance obtained using Monte Carlo average from  $M = 200$  simulated samples based on  $\int_0^1 E\{[\hat{\mu}_L(t) - \mu(t)]^2\} dt = \int_0^1 \{E[\hat{\mu}_L(t)] - \mu(t)\}^2 dt + \int_0^1 \{E[\hat{\mu}_L(t)] - \mu(t)\}^2 dt$ . The asymptotic integrated squared bias and variance are given by

$$AIBIAS = \frac{1}{2} \sigma_{K_1}^2 b^4, \quad AIVAR = \frac{0.02 \times \|K_1\|^2}{n \bar{N} b}, \tag{20}$$

and the asymptotic integrated mean squared error  $AIMSE = AIBIAS + AIVAR$ , here  $\sigma_{K_1}^2 = \int u^2 K_1(u) du$ ,  $\|K_1\|^2 = \int K_1^2(u) du$  and  $\bar{N} = (1/n) \sum_{i=1}^n N_i$ , while the empirical integrated squared bias, variance and mean squared error are denoted by EIBIAS, EIVAR and EIMSE,

The asymptotic and empirical quantities, such as the integrated squared bias, variance and mean squared error, are shown in Fig. 1 for the correlated/independent data with sample size  $n = 50/n = 200$ , respectively. From Fig. 1, it is obvious that the asymptotic approximation is improved by increasing the sample size. The asymptotic quantities AIBIAS, AIVAR and AIMSE agree with the

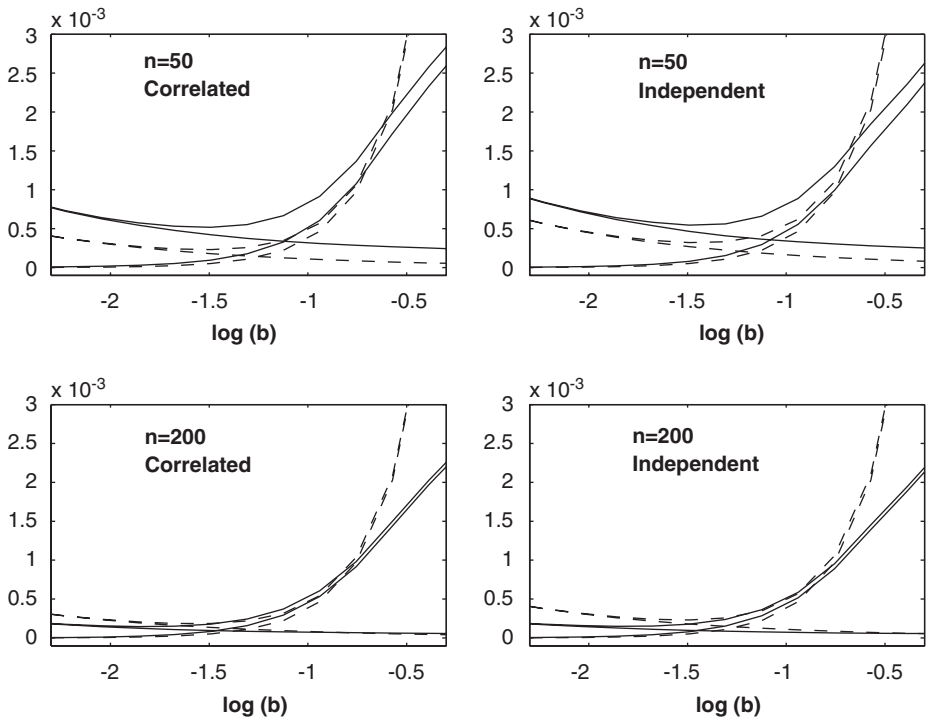


Fig. 1. Shown are the empirical quantities (solid, including EIBIAS, EIVAR, EIMSE) and asymptotic quantities (dashed, including AIBIAS, AIVAR, AIMSE) versus  $\log(b)$  for correlated (left panel) and independent (right panel) data with different sample size  $n = 50$  (top panel) and  $n = 200$  (bottom panel), where  $b$  is the bandwidth used in the smoothing. In each panel, the integrated bias is the one with increasing pattern, the integrated variance is the one with decreasing pattern, and the cross each other, while the integrated mean squared error, which is larger than both integrated bias and variance for a bandwidth  $b$ , all decrease first and then increase after reaching a minimum.

empirical quantities EIBIAS, EIVAR and EIMSE for both correlated and independent data. For the simulated data with the same sample size  $n$ , the asymptotic approximation for correlated and independent data are well comparable in pattern and magnitude. This provides the evidence that the within-subject correlation indeed does not have obvious influence on the asymptotic behavior of the local polynomial estimator compared to the standard rate obtained from independent data, which is consistent with our theoretical derivation.

### 6. Discussion

In this paper, the asymptotic distribution of kernel-based nonparametric regression estimator for functional longitudinal data are studied. In particular, it is shown that  $D_{0.6}(c_{0.6})^{-1} \rightarrow D_{0.6}(c_{0.6})^{-1}$  for  $D_{0.6}(c_{0.6})^{-1} \rightarrow D_{0.6}(c_{0.6})^{-1}$ .



design described in (A1.1) and (A1.2), fixed equally spaced design described in (A1\*), and some correlation between them. The proposed self-consistent estimator could also be extended to more complicated case, such as panel data where observations for different subjects are obtained at a series of common time points during a longitudinal follow-up. If considering random design, the density of the  $j$ th observation time  $T_j$  could be assumed to be  $f_j(t)$ , then the results are readily applied to this case with appropriate modification with respect to the different marginal densities.

The general asymptotic distribution results in univariate and bivariate smoothing setting are applied to the kernel-based estimator of the mean and covariance function, which yield asymptotic normal distribution of the estimator. To the best of our knowledge, there are no asymptotic distribution results available in literature for nonparametric estimator of covariance function obtained from observed noisy longitudinal or functional data. This provides theoretical basis and practical guidance for the nonparametric analysis of functional or longitudinal data with important potential application that are based on the asymptotic distribution. For example, asymptotic confidence band or region for the regression curve or the covariance surface can be constructed based on their asymptotic distribution. Since, due to their heavy computational load, commonly used procedures (such as cross-validation) for bandwidth selection in  $d$ -dimensional setting are not feasible, one important research problem is to seek efficient approaches for choosing smoothing parameter. Also, functional principal component analysis, an increasingly popular tool for functional data analysis, is based on eigen-decomposition of the estimated covariance function. Thus, the influence of the asymptotic properties of covariance estimator on the estimated eigenfunction is another potential research of interest.

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