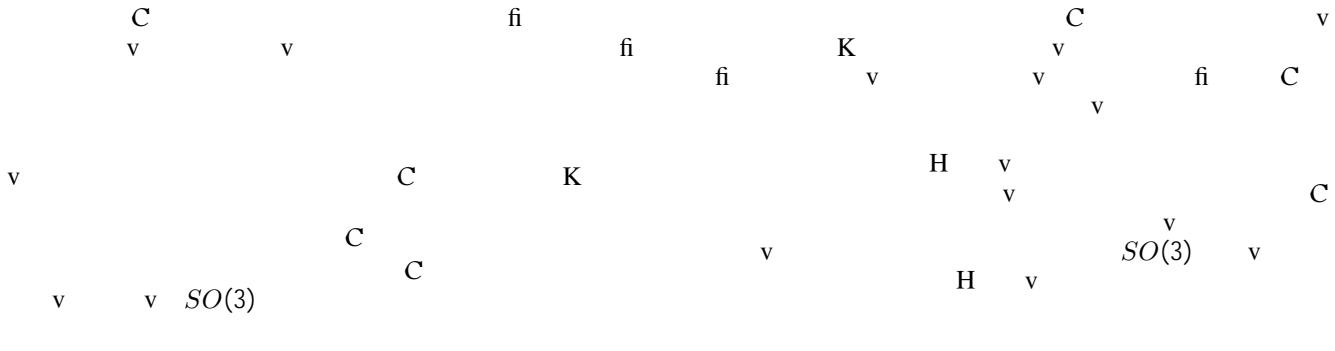


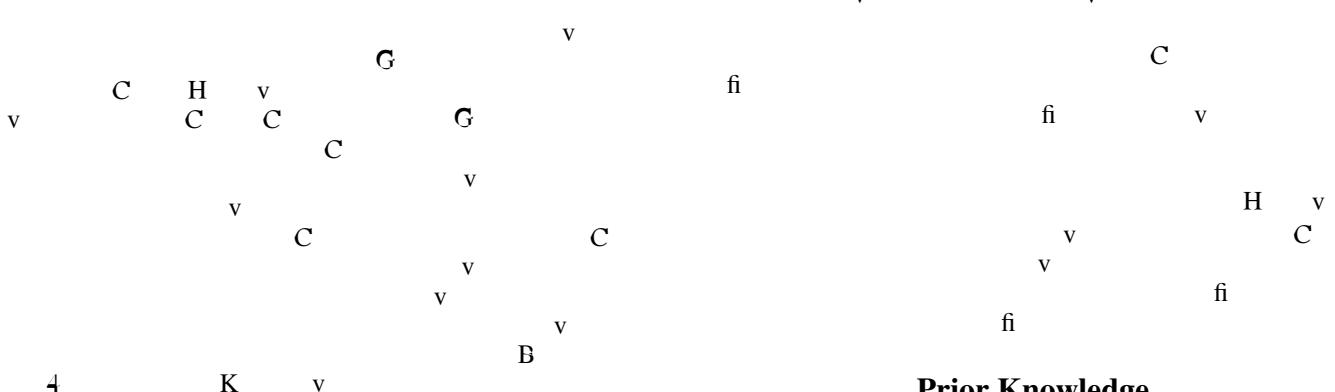
PDO-eS²CNNs: Partial Differential Operator Based Equivariant Spherical CNNs

Zhengyang Shen , Tiancheng Shen , Zhouchen Lin ^{4,5} , Jinwen Ma

\mathcal{S}^2			$SO(2), SO(3)$		
α, β, γ			$Z(\alpha)Y(\beta)$		$z \quad y$
R	$R \in SO(3)$	$R = Z(\alpha_R)Y(\beta_R)Z(\gamma_R)$	$n = (0, 0, 1)^T$		
P	$P \in \mathcal{S}^2$	$P(\alpha, \beta) = Z(\alpha)Y(\beta)n$	\bar{P}		$v \quad F$
$\bar{P} \cdot SO(2)$	$\{\bar{P}Z(\gamma) \gamma \in [0, 2\pi)\}$	$SO(2)$	$E \simeq F$	E	\mathcal{S}^2
A_R		$Z(\gamma_R)$	$C^\top(\mathcal{S}^2)$		$so \in C^\top(SO(3))$
$C^\top(SO(3))$		$SO(3)$	s, so	\mathcal{S}^2	P
$\pi_{\bar{R}}^S[s], \pi_{\bar{R}}^{SO}[so]$	\tilde{R}	$s \quad so$	U_P		$U_P \quad \tilde{U}_P$
\bar{U}_p	$\tilde{U}_p = \varphi_P(U_P) \subset \mathbb{R}^2$		φ_P		w
\bar{s}		\mathbb{R}^3	$H(\cdot, \cdot; w)$		
$\partial/\partial x_i^{(A)}$		$A \in SO(2)$	$\nabla_x[f], \nabla_x^2[f]$	H	f
$\nabla_x^{(A)}, (\nabla_x^{(A)})^2$	fi		$\chi^{(A)}$		fi
Ψ, Φ	fi		\mathbf{I}, \mathbf{F}		•
f_P	$f_P = \bar{s} \cdot \varphi_P^{-1}$		$O(\cdot)$	fi	
D_P, \hat{D}_P	v	v	$\hat{\nabla}_x[f], \hat{\nabla}_x^2[f]$		$\nabla_x[f] \quad \nabla_x^2[f]$
$\tilde{\chi}^{(A)}, \tilde{\Psi}, \tilde{\Phi}$		$\chi^{(A)}, \Psi \quad \Phi$	C_N	N	



Related Work



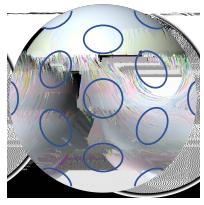
Prior Knowledge

Parameterization of S^2 and $SO(3)$

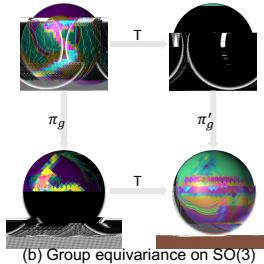
$$\begin{array}{ccc} \mathcal{S}^2 & SO(3) \\ & \vee \end{array}$$

$$\mathcal{S}^2 = \{(1, 2, 3) | \| \cdot \|_2 = 1\},$$

$$SO(3) = \{R \in \mathbb{R}^3 | R^T R = I, \det(R) = 1\}.$$



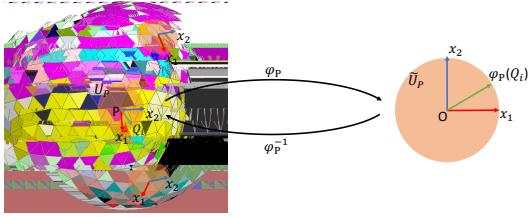
(a) $S^2 \simeq SO(3)/SO(\)$



(b) Group equivariance on $SO(3)$

$$\begin{array}{ccc} S^2 \simeq & SO(3)/SO(2) & SO(3) \\ v & & G \\ g \in & SO(3) & \\ v & \text{if} & \\ & & T \\ & & v \\ & & v \end{array}$$

Rn $R \in SO(3)$ $SO(3)$
 $R = Z(\alpha_R)Y(\beta_R)Z(\gamma_R),$ S10 8Z966



$$P \in \mathcal{S}^2 \quad U_P \subset \mathcal{S}^2 \quad \tilde{U}_P \subset \mathbb{R}^2 \quad \varphi_P$$

$$\varphi_P(P) = 0 \quad \varphi_P \quad \tilde{U}_P = \varphi_P(U_P) \subset \mathbb{R}^2$$

$$\varphi_P^{-1}(v_1, v_2) = P \left(v_1, v_2, \sqrt{1 - |v|^2} \right)^T.$$

$$\varphi_P \quad \begin{matrix} 1 & 2 \\ \text{fi} & \text{fi} \\ v & v \end{matrix} \quad \begin{matrix} U_P \\ \text{fi} \\ v \end{matrix} \quad P \in \mathcal{S}^2$$

$$\in C^\infty(\mathcal{S}^2) \quad \begin{matrix} v \\ \text{fi} \end{matrix} \quad \mathbb{R}^3$$

$$\in C^\infty(\mathbb{R}^3) \quad \begin{matrix} v \\ \text{fi} \end{matrix}$$

$$\partial^2/\partial v_i \partial v_j (\cdot, \cdot) = 1, 2$$

$$\cdot \varphi_P^{-1} \in C^\infty(\mathbb{R}^2) \quad \forall P \in \mathcal{S}^2$$

$$\frac{\partial}{\partial v_i} [\cdot](P) = \frac{\partial}{\partial v_i} [\cdot \varphi_P^{-1}] (0),$$

$$\frac{\partial^2}{\partial v_i \partial v_j} [\cdot](P) = \frac{\partial^2}{\partial v_i \partial v_j} [\cdot \varphi_P^{-1}] (0).$$

$$\text{B} \quad \begin{matrix} \text{fi} \\ \text{fi} \end{matrix} \quad \begin{matrix} v \\ v \end{matrix} \quad \begin{matrix} \text{fi} \\ \text{fi} \end{matrix} \quad \begin{matrix} v \\ v \end{matrix} \quad \begin{matrix} H \\ H \end{matrix}$$

$$\text{B} \quad \begin{matrix} v \\ v \end{matrix}$$

$$\begin{matrix} \text{fi} & & v & & \text{fi} & & \text{fi} & & v \\ \text{fi} & & v & & v & & \text{fi} & & v \end{matrix}$$

Rotated Parameterized Differential Operators

$$\begin{matrix} & & H \\ & & \text{H} \\ & v & & & H \\ & \text{fi} & & & 2v \end{matrix}$$

$$H(r, \theta; \mathbf{w}) = w_1 + w_2 r + w_3 + w_4 r^2 + w_5 r^3 + w_6 r^4,$$

[.]

$$\begin{aligned} \frac{\partial}{\partial v_1} &= \frac{\partial}{\partial v_2} & H(\frac{\partial}{\partial v_1}, \frac{\partial}{\partial v_2}; \mathbf{w}) &= \\ H(r, \theta; \mathbf{w}) &= r^2 + r & H(\frac{\partial}{\partial v_1}, \frac{\partial^2}{\partial v_1^2}; \mathbf{w}) &= \\ \frac{\partial^2}{\partial v_1^2} + \frac{\partial^2}{\partial v_2^2} & & 2 \times 2 & \\ & & & A \in SO(2) \end{aligned}$$

$$\chi^{(A)} = H \left(\frac{\partial}{\partial v_1^{(A)}}, \frac{\partial}{\partial v_2^{(A)}}; \mathbf{w} \right), \quad 4$$

$$\left(\frac{\partial}{\partial v_1^{(A)}}, \frac{\partial}{\partial v_2^{(A)}} \right)^T = A^{-1} \left(\frac{\partial}{\partial v_1}, \frac{\partial}{\partial v_2} \right)^T. \quad 5$$

$$\nabla_x^{(A)} = A^{-1} \nabla_x, \quad 5$$

$$\nabla_x = \left(\frac{\partial}{\partial v_1}, \frac{\partial}{\partial v_2} \right)^T \quad Z$$

$$\begin{aligned} \left(\nabla_x^{(A)} \right)^2 &:= \begin{bmatrix} \frac{\partial}{\partial x_1^{(A)}} \frac{\partial}{\partial x_1^{(A)}} & \frac{\partial}{\partial x_1^{(A)}} \frac{\partial}{\partial x_2^{(A)}} \\ \frac{\partial}{\partial x_1^{(A)}} \frac{\partial}{\partial x_2^{(A)}} & \frac{\partial}{\partial x_2^{(A)}} \frac{\partial}{\partial x_2^{(A)}} \end{bmatrix} \\ &= A^{-1} \begin{bmatrix} \frac{\partial^2}{\partial x_1^2} & \frac{\partial^2}{\partial x_1 \partial x_2} \\ \frac{\partial^2}{\partial x_1 \partial x_2} & \frac{\partial^2}{\partial x_2^2} \end{bmatrix} A = A^{-1} \nabla_x^2 A. \end{aligned}$$

$$\begin{matrix} \text{fi} & \chi^{(A)} \\ \partial/\partial v_2^{(A)} & \text{fi} \\ \partial/\partial v_1^{(A)} & \text{fi} \end{matrix}$$

$$\begin{aligned} &= w_1 + (w_2 \cdot w_3) \nabla_x^{(A)} + \left\langle \begin{bmatrix} \frac{w_4}{w_5} & \frac{w_5}{w_6} \\ \frac{w_5}{w_2} & w_6 \end{bmatrix} ; \left(\nabla_x^{(A)} \right)^2 \right\rangle \\ &= w_1 + (w_2 \cdot w_3) A^{-1} \nabla_x + \left\langle \begin{bmatrix} \frac{w_4}{w_5} & \frac{w_5}{w_6} \\ \frac{w_5}{w_2} & w_6 \end{bmatrix} ; A^{-1} \nabla_x^2 A \right\rangle \\ &= w_1 + (w_2 \cdot w_3) A^{-1} \nabla_x + \left\langle A \begin{bmatrix} \frac{w_4}{w_5} & \frac{w_5}{w_6} \\ \frac{w_5}{w_2} & w_6 \end{bmatrix} A^{-1} ; \nabla_x^2 \right\rangle; \end{aligned}$$

$$\begin{matrix} \langle \cdot, \cdot \rangle & \chi^{(A)} & \mathbf{w} \\ \text{fi} & \text{fi} & \text{v} \\ \text{v} & \text{v} & \text{fi} \end{matrix}$$

$$\begin{matrix} C & \chi^{(A)} & C \\ & B & \\ C & C & C \end{matrix}$$

Equivariant Differential Operators

$$\begin{matrix} \text{fi} & & v \\ \chi^{(A)} & & \text{fi} \\ & & \text{fi} \end{matrix}$$

Theorem 1 If $\psi \in C^\infty(\mathcal{S}^2)$ and $\phi \in C^\infty(SO(3))$, $\forall \tilde{R} \in SO(3)$, we have

$$\left[\pi_{\tilde{R}}^S [\quad] \right] = \pi_{\tilde{R}}^{SO} [\quad [\quad]],$$

$$\left[\pi_{\tilde{R}}^{SO} [\quad] \right] = \pi_{\tilde{R}}^{SO} [\quad [\quad]].$$

Equivariant Network Architectures

$$V \quad V$$

fi
fi
v

$$\sigma(\cdot) \quad U \quad v$$

$$T[] = {}^{(L)} \left[\cdots \sigma \left({}^{(1)} [\sigma([])] \right) \right]$$

Theorem 2 If $\in C^\infty(\mathcal{S}^2)$, $\forall \tilde{R} \in SO(3)$, we have

$$T \left[\pi_{\widetilde{R}}^S [\quad] \right] = \pi_{\widetilde{R}}^{SO} [T [\quad]].$$

Implementation Icosahedral Spherical Mesh

Estimation of Partial Derivatives

$$\hat{D}_P = \arg \min_D \|V_P D - F_P\|_2 = (V_P^T V_P)^{-1} V_P^T F_P.$$

Discretization of $SO(2)$

$$C_N \quad C_N = \{e = A_0, A_1, \dots, A_{N-1}\}$$

$$A_i = \begin{bmatrix} \cos \frac{2\pi i}{N} & -\sin \frac{2\pi i}{N} \\ \sin \frac{2\pi i}{N} & \cos \frac{2\pi i}{N} \end{bmatrix}.$$

$$\forall P \in$$

$$= 0, 1, \dots, N-1$$

$$\begin{aligned}
& \widetilde{\Psi}[\mathbf{I}](P; i) = {}^{*(A_i)}[\mathbf{I}](P) \\
&= \left(w_1 + (w_2; w_3) A_i^{-1} \hat{\nabla}_x + \left\langle A_i \begin{bmatrix} W_4 & \frac{w_5}{2} \\ \frac{w_5}{2} & W_6 \end{bmatrix} A_i^{-1}; \hat{\nabla}_x^2 \right\rangle \right) [f_P] (0) \\
&= w_1 f_P(0) + (w_2; w_3) A_i^{-1} \hat{\nabla}_x [f_P] (0) \\
&\quad + \left\langle A_i \begin{bmatrix} W_4 & \frac{w_5}{2} \\ \frac{w_5}{2} & W_6 \end{bmatrix} A_i^{-1}; \hat{\nabla}_x^2 [f_P] (0) \right\rangle;
\end{aligned}$$

$$\begin{aligned} & \text{v} \quad \text{v} & I & \sim [I] \\ & \overset{\text{v}}{N} & \text{fi} & \\ A \in SO(2) & & & \forall P \in \\ \text{•} = 0, 1, \dots, N-1 & & & \\ & \sim [\mathbf{F}](P, \cdot) = \frac{\nu(SO(2))}{N} \sum_{j=0}^{N-1} \tilde{\chi}_{Z_j}^{(\mathcal{Z}_i)} [\mathbf{F}](P, \cdot \circlearrowleft), & & \\ & \mathbf{F} & N & \\ C^\infty(SO(3)) & \mathbf{F}(P, \cdot) = \underset{(P, A_i)}{\sim} \circlearrowleft & & \in \\ & \overset{N}{\text{C}} \quad \overset{\text{v}}{5} & & \\ & \text{v} \quad \text{v} & \text{C} \quad \text{v} & \end{aligned}$$

Equivariance Error Analysis

$$O(\rho_m) \quad \begin{matrix} v \\ \text{fi} \\ O(\rho_i) = O(\rho) \\ v \end{matrix} \quad O(\rho_1) = O(\rho_2) = \dots = O(\rho_n)$$

Theorem 3 $\forall \tilde{R} \in SO(3)$,

$$\sim \left[\pi_{\tilde{R}}^S[\mathbf{I}] \right] = \pi_{\tilde{R}}^{SO} \left[\sim [\mathbf{I}] \right] + O(\rho), \quad 4$$

$$\tilde{\left[\pi_{\tilde{R}}^{SO}[\mathbf{F}] \right]} = \pi_{\tilde{R}}^{SO} \left[\tilde{[F]} \right] + O(\rho) + O\left(\frac{1}{N^2}\right), \quad 5$$

where transformations acting on discrete inputs and feature maps are defined as $\pi_R^S[\mathbf{I}](P) = \pi_{\bar{R}}^S[\mathbf{I}](P)$ and $\pi_R^{SO}[\mathbf{F}](P, \cdot) = \pi_{\bar{R}}^{SO}[\mathbf{F}](P, A_i)$, respectively.

Experiments

Experiments

Spherical MNIST Classification

C

V V

V V

V 4

V V

V V

v 99.44%

90.14% v

H U C v

v H v

fi v C

45 v v fi v v

				#
C C	✓	96	94	95
G C	✗	99.23	35.60	94.92
H U C	✗	99.45	29.84	97.05
PDO-eS²CNN	✓	99.44 ± 0.06	90.14 ± 0.58	98.93 ± 0.08
C C G	✗	94.4		
C K v	✓	96.4	96	96.6
C C	✓	99.43	69.99	99.31
PDO-eS²CNN	✓	99.60 ± 0.04	94.25 ± 0.29	99.45 ± 0.05

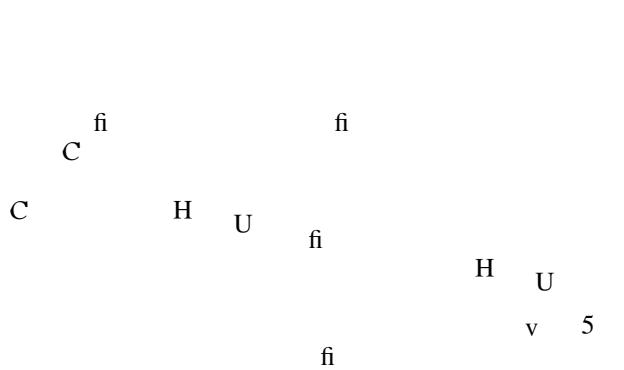
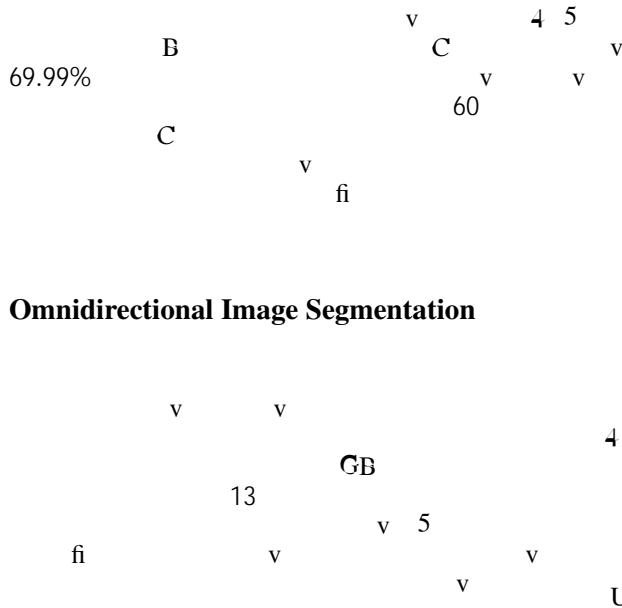
v

		U	#
U	5	5	
C	55	4	
G C	5		
H U	54		5
5	5	4	5
PDO-eS²CNN	60.4 ± 1.0	44.6 ± 0.4	

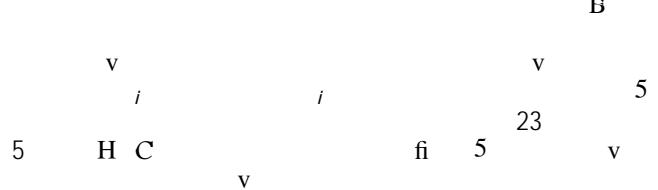
v 5 U

4

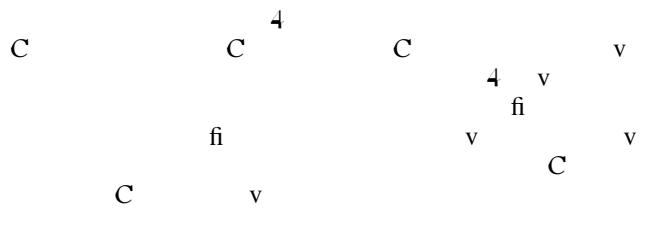
fi



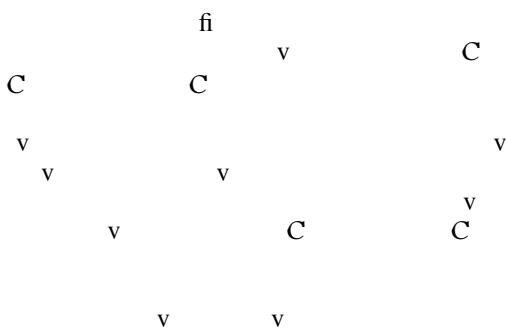
Atomization Energy Prediction



Omnidirectional Image Segmentation



Conclusions



Acknowledgements

```

graph LR
    KB1[KB] -- v --> Node1(( ))
    KB1 -- 5 --> C1[C]
    C1 -- C --> Node2(( ))
    C1 -- fi --> KB2[KB]
    KB2 -- KB --> Node3(( ))
    KB2 -- C --> Node1
  
```

References

<i>ArXiv e-prints</i>	<i>U</i>
B	5
<i>Numerical Analysis</i>	5
B C	
U v <i>lcal Society</i>	G B V 5
	<i>Journal of the American Chemical Society</i>
B	C v
<i>NeurIPS</i> 4 44	
B B G	G V
4 4 4	<i>IEEE Signal Processing Magazine</i>
B C	
G ICLR	C
C G C	G v
C	<i>NeurIPS</i> 4 4 4 45
	H
VV	GB
v	<i>International Conference on 3D Vision (3DV)</i>
C C G	K
	<i>ICLR</i>
C G C v	K C v
	<i>ICML</i>
C v	G v C
C B C	G
5 5 54	C fi
	ECCV
G	
G	<i>ICLR</i>
C	
G	
B	
<i>ICRA</i> 45 45	

G **K** 360°

5 5

G **B** **C** **v**
v **V** **C** *NeurIPS*

C **C**

ICCV 5 54

C **C** **G** *IJ-*

CAI 4